

## Last Time: Bases and Exchange.

Recall: If  $V$  is a vector space w/ finite basis  $B$ , then every basis of  $V$  has the same number of elements as  $B$ .

NB: We don't actually need the finiteness assumption...  
We won't (however) prove that  $\equiv$

Def<sup>n</sup>: Let  $V$  be a vector space. The dimension of  $V$  is the size of any of its bases.

Notation:  $\dim(V)$  = dimension of  $V$ .

Ex: Let  $n \geq 0$ . The dimension of  $\mathbb{R}^n$  is  $n$ .  
because  $E_n = \{e_1, \dots, e_n\}$  the standard basis, has  $n$  elts

Ex: Compute dimension of

$$V = \{a_0 + a_1x + a_2x^2 + a_3x^3 : a_0 + a_1 = 0 = a_2 - a_3\} \subseteq \mathcal{P}_3(\mathbb{R}).$$

Sol: Let's compute a basis of  $V$ :

$$a_0 + a_1 = 0 \iff a_1 = -a_0$$

$$a_2 - a_3 = 0 \iff a_3 = a_2, \quad \text{so}$$

$$V = \{a_0 - a_0x + a_2x^2 + a_2x^3 : a_0, a_2 \in \mathbb{R}\} \leftarrow$$

$\therefore$  every polynomial in  $V$  has form:

$$a_0(1-x) + a_2(x^2+x^3).$$

Hence  $B = \{1-x, x^2+x^3\}$  is a spanning set for  $V$ .

Check:  $B$  is lin ind.

Hence  $B = \{1-x, x^2+x^3\}$  is a basis of  $V$ .

$$\text{So } \dim(V) = \#B = |B| = 2 \text{ number of elements in } B.$$



Ex: Compute  $\dim(V)$  for  $V = \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} : \underline{a+b+c=0=a+b-c}, d \in \mathbb{R} \right\}$

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Sol: Compute a basis for  $V$ :

$$\left. \begin{aligned} a+b+c=0 &\Leftrightarrow a+b=-c \\ a+b-c=0 &\Leftrightarrow a+b=c \end{aligned} \right\} \Rightarrow \begin{aligned} c &= -c \\ \Leftrightarrow c &= 0 \end{aligned}$$

$$\therefore V = \left\{ \begin{pmatrix} a & b \\ 0 & d \end{pmatrix} : a+b=0, d \in \mathbb{R} \right\}$$

$$\therefore a+b=0 \Leftrightarrow b=-a$$

$$\therefore V = \left\{ \begin{pmatrix} a & -a \\ 0 & d \end{pmatrix} : a, d \in \mathbb{R} \right\}$$

$$= \left\{ a \begin{pmatrix} 1 & -1 \\ 0 & 0 \end{pmatrix} + d \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} : a, d \in \mathbb{R} \right\}$$

$B = \left\{ \begin{pmatrix} 1 & -1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right\}$  is a spanning set for  $V$ .

$B$  is also Lin. indep. Hence  $B$  is a basis,

$$\text{so } \dim(V) = \#B = 2$$

□

The following corollaries are nice exercises  
(all follow from the propositions proved last time).

Prop: Every vector space has a basis. ← know this...

↳ Follows from Zorn's Lemma, which is equivalent to Axiom of Choice... Don't need to know these...

Cor: Every independent set can be expanded to a basis.

Cor: Every spanning set can be reduced to a basis.

Cor: If  $I \subseteq V$  is independent, then  $\#I \leq \dim(V)$

Cor: If  $V$  is finite dimensional, then every spanning set with  $\dim(V)$  vectors is a basis.

# Linear Maps

Recall: We've seen linear maps before:  $\mathbb{R}^n \rightarrow \mathbb{R}^m$ .

We'll extend the definition to arbitrary vector spaces:

Def<sup>n</sup>: A function  $L: V \rightarrow W$  of vector spaces is linear (i.e. a linear map or linear homomorphism) when for all  $c \in \mathbb{R}$  and all  $x, y \in V$  we have both:  
 $L(cx) = cL(x)$  and  $L(x+y) = L(x) + L(y)$ .

Ex: The projections are linear maps (i.e. maps which forget components).

$$p: \mathbb{R}^3 \rightarrow \mathbb{R}^2 \text{ w/ } p\left(\begin{pmatrix} x \\ y \\ z \end{pmatrix}\right) = \begin{pmatrix} x \\ y \end{pmatrix}$$

$$q: \mathbb{R}^3 \rightarrow \mathbb{R}^2 \text{ w/ } q\left(\begin{pmatrix} x \\ y \\ z \end{pmatrix}\right) = \begin{pmatrix} x \\ z \end{pmatrix}$$

$$s: \mathbb{R}^4 \rightarrow \mathbb{R} \text{ w/ } s\left(\begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix}\right) = w$$

all linear!

To see  $p$  is linear,

$$p\left(c\begin{pmatrix} x \\ y \\ z \end{pmatrix}\right) = p\begin{pmatrix} cx \\ cy \\ cz \end{pmatrix} = \begin{pmatrix} cx \\ cy \end{pmatrix} = c\begin{pmatrix} x \\ y \end{pmatrix} = c p\left(\begin{pmatrix} x \\ y \\ z \end{pmatrix}\right)$$

$$\begin{aligned} p\left(\begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} + \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix}\right) &= p\begin{pmatrix} x_1 + x_2 \\ y_1 + y_2 \\ z_1 + z_2 \end{pmatrix} = \begin{pmatrix} x_1 + x_2 \\ y_1 + y_2 \end{pmatrix} = \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} + \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} \\ &= p\begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} + p\begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix} \end{aligned}$$

$\therefore p(cx) = cp(x)$  and  $p(x+y) = p(x) + p(y)$  for all  $c \in \mathbb{R}$  and  $x, y \in \mathbb{R}^3$ . Hence  $p$  is linear  $\square$

Ex: The map  $L: \mathcal{P}_2(\mathbb{R}) \rightarrow \mathbb{R}^3: c + bx + ax^2 \mapsto \begin{pmatrix} a \\ b \\ c \end{pmatrix}$  is a linear map.

Earlier in the course, we proved the following:

\* Lem: If  $L: V \rightarrow W$  is linear, then  $L(0_V) = 0_W$ .

Prop (Alt. Characterization of Linear Maps): Let  $L: V \rightarrow W$  be a function. The following are equivalent:

①  $L$  is a linear map.

② For all  $c \in \mathbb{R}$  and all  $x, y \in V$ , we have both

$\downarrow$   $L(cx) = cL(x)$  and  $L(x+y) = L(x) + L(y)$ .

\* ③ For all  $c \in \mathbb{R}$  and all  $x, y \in V$ , we have  $L(x + cy) = L(x) + cL(y)$ . ← easiest condition to check...

\* ④ For all  $c_1, c_2, \dots, c_n \in \mathbb{R}$  and all  $x_1, x_2, \dots, x_n \in V$  we have

useful →  $L(c_1x_1 + c_2x_2 + \dots + c_nx_n) = c_1L(x_1) + c_2L(x_2) + \dots + c_nL(x_n)$ .  
(i.e.  $L$  preserves all linear combinations).

Exercise: Rework the old proofs into proofs for this case...

Ex: Is  $L: \mathcal{P}_2(\mathbb{R}) \rightarrow M_{2 \times 2}(\mathbb{R})$  w/

$$L(\underline{c} + \underline{b}x + \underline{a}x^2) = \begin{pmatrix} a & b \\ c & a+b \end{pmatrix} \quad \text{linear?}$$

Sol: We check our condition:

$$L\left((c_1 + b_1x + a_1x^2) + d(c_2 + b_2x + a_2x^2)\right) \stackrel{?}{=} L(c_1 + b_1x + a_1x^2) + dL(c_2 + b_2x + a_2x^2)$$

$$L((c_1 + b_1x + a_1x^2) + d(c_2 + b_2x + a_2x^2))$$

$$= L((c_1 + dc_2) + (b_1 + db_2)x + (a_1 + da_2)x^2)$$

$$= \begin{pmatrix} \underline{a_1 + da_2} & \underline{b_1 + db_2} \\ \underline{c_1 + dc_2} & (\underline{a_1 + da_2}) + (\underline{b_1 + db_2}) \end{pmatrix}$$

$$= \begin{pmatrix} a_1 & b_1 \\ c_1 & a_1 + b_1 \end{pmatrix} + \begin{pmatrix} da_2 & db_2 \\ dc_2 & da_2 + db_2 \end{pmatrix}$$

$$= \begin{pmatrix} a_1 & b_1 \\ c_1 & a_1 + b_1 \end{pmatrix} + d \begin{pmatrix} a_2 & b_2 \\ c_2 & a_2 + b_2 \end{pmatrix}$$

$$L(c + bx + ax^2) = \begin{pmatrix} a & b \\ c & a+b \end{pmatrix}$$

$$= L(c_1 + b_1x + a_1x^2) + d L(c_2 + b_2x + a_2x^2)$$

Hence  $L$  is linear by Alt. Char. of Linearity.  $\square$

Non-Ex: The map  $L: \mathbb{R}^3 \rightarrow \mathbb{R}^2$  w/  $L\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x-y \\ z+1 \end{pmatrix}$  is NOT linear!

Lemma:  $L(0_V) = 0_W$   
for linear  $L: V \rightarrow W$ .

$$L\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0-0 \\ 0+1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix},$$

So  $L(0_{\mathbb{R}^3}) \neq 0_{\mathbb{R}^2}$  yields  $L$  is not linear.

Prop: Let  $L: V \rightarrow W$  be linear and let  $V$  have a basis  $B$ . Then  $L$  is determined by its action on  $B$ .

Point: Given  $v \in V$ ,  $v = \sum_{i=1}^n c_i b_i$ . Thus:

$$L(v) = L\left(\sum_{i=1}^n c_i b_i\right)$$

$$= L(c_1 b_1 + c_2 b_2 + \dots + c_n b_n)$$

$$= c_1 L(b_1) + c_2 L(b_2) + \dots + c_n L(b_n).$$

Prop: Let  $V, W$  be vector spaces. Let  $B$  be a basis of  $V$ . Every function  $f: B \rightarrow W$  extends (linearly) to a linear map  $F: V \rightarrow W$ . Indeed:

$$F\left(\sum_{i=1}^n c_i b_i\right) = \sum_{i=1}^n c_i f(b_i).$$

Point: Given a function associating vectors of basis  $B$  to vectors of  $W$ , there is a corresponding induced linear map...

Ex: Let  $V = \mathbb{R}^3$  and  $W = M_{2 \times 3}(\mathbb{R})$ .

Define  $f: E_3 \rightarrow W$  by:

$$f(e_1) = \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \end{pmatrix}, \quad f(e_2) = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix},$$

$$f(e_3) = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}. \quad \text{The induced map}$$

$F: \mathbb{R}^3 \rightarrow M_{2 \times 3}(\mathbb{R})$  is

$$\begin{aligned} F\begin{pmatrix} x \\ y \\ z \end{pmatrix} &= F(xe_1 + ye_2 + ze_3) \\ &= xf(e_1) + yf(e_2) + zf(e_3) \\ &= x\begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \end{pmatrix} + y\begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} + z\begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \\ &= \begin{pmatrix} x+z & 0 & 2x+y+z \\ 0 & x+z & x+y \end{pmatrix} \end{aligned}$$

And  $F$  is a linear map! ☺ □